Given a single connected contour, which is either convex or non-convex (concave), use any algorithm to find its **Convex Hull**, i.e., the smallest convex contour enclosing the given shape. If the given contour is convex, then its convex hull is the original contour itself. The maximal size of the shape is 512×512 , and the maximal number of the vertices of the shape is 512. Write a program to read the input data (the given shapes) from a disk file, implement your convex hull finding algorithm, and then output the shape data of the results to the standard output.

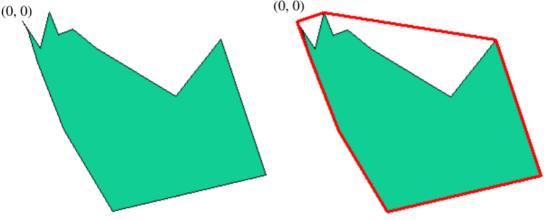
Input

The order of the vertices is counterclockwise in X - Y Cartesian Plane (if you consider the origin of the display window is on the upper-left corner, then the orientation of the vertices is clockwise), and none of the neighboring vertices are co-linear. Since all the shapes are closed contours, therefore, the last vertex should be identical to the first vertex. There are several sets of data within a given data file. The negative number '-1' is used to separate the data set.

Line	Data in	
Number	the File	Explanation
1	K	a positive integer showing how many sets of data in this file
2	N	a positive integer showing the number of vertices for the shape
3	$X_1 Y_1$	two positive integers for the first vertex (X_1, Y_1)
4	$X_2 Y_2$	two positive integers for the next neighboring vertex (X_2, Y_2)
N+2	$X_N Y_N$	two positive integers for the last vertex (X_N, Y_N)
N+3	-1	Delimiter
N+4	M	a positive integer showing the number of vertices for the next shape
N+5	$XX_1 YY_1$	two positive integers for the first vertex

Note: Please note that the **Line Number**, **Data in the File** and **Explanation** are not given in the file. They are shown here only to assist you in reading the data.

The contour shape of the first dataset as well as its convex hull is shown in the following figure:



Output

Output the convex hull of all K input shapes to the standard output. The data format should be the same as the input file. In addition, the vertex with the smallest Y value should be the first point and if there are points with the same Y value, then the smallest X value within those points should be the first point.

Sample Input