Given $n$ points and $m$ planes in 3D place, you will need to perform $t$ transformations on them, and then calculate their final states. By "transforming a plane", we mean transforming all the points on that plane.

There are three kinds of transformations (in the text below, $P$ means the point being transformed):

| TRANSLATE $a b c$ | If $P$ 's position was $(x, y, z)$, it becomes $(x+a, y+b, z+c)$ after the trans- <br> formation. |
| :--- | :--- |
| ROTATE $a b c$ theta | $P$ is rotated. The rotation axis is vector $(a, b, c)$, the angle of rotation is <br> theta degrees. The rotation follows the right-hand rule, so if the vector <br> $(a, b, c)$ points toward you, the rotation will be counterclockwise from your <br> point of view. The rotation axis always passes through $(0,0,0)$. |
| SCALE $a b c$ | If $P$ 's position was $(x, y, z)$, it becomes $(a x, b y, c z)$ after the transformation. |

This problem uses right-hand coordinate system:

## Input

There will be only one test case, beginning with three integers $n, m, t$ ( $1 \leq n, m \leq 50,000,1 \leq t \leq 1,000)$. Next $n$ lines contain the coordinates of each point. Next $m$ lines contains four integers $a, b, c, d$ to describe a

plll $a x+b y+c z+d=0$ (at least one of $a, b, c$ will be non-zero). Next $t$ hes contain the operations All the input coordinates and parameters $a, b, c, d$ are real numbers with absolute values not larger than 10. These input real numbers will have at most two digits after the decimal point. Parameter theta is an integer between 0 and 359 (inclusive).

## Output

For each point, print three real numbers $x, y, z$ on a single line. For each plane, print four real numbers $a, b, c, d$ on a single line. To avoid floating-point issues, $a^{2}+b^{2}+c^{2}$ must be 1 , but if there is more than one choice of $(a, b, c, d)$ to represent the answer, anyone is acceptable. Output each real number to two decimal places. To reduce the impact of floating-point errors, each number you print could differ from the standard output by up to 0.05 .

## Sample Input

## 113

123
001 -2
TRANSLATE 234
ROTATE 10090
SCALE 321

## Sample Output

$9.00-14.005 .00$
0.001 .000 .0012 .00

